

RADAR SYSTEMS

OBJECTIVES

The student will be introduced to:

1. The Basic Principle of radar and radar range equation.
2. Different types of radars; CW, FM-CW, MTI and pulse Doppler radars.
3. Understand the different tracking techniques for radar.
4. Understand the characteristics of a matched filter receiver and its performance.
5. Understand the different types of displays, duplexers and antennas used in radar systems.

UNIT-I:

Basics of Radar : Introduction, Maximum Unambiguous Range, simple Radar range Equation, Radar Block Diagram and Operation, Radar Frequencies and Applications. Prediction of Range Performance, Minimum Detectable Signal, Receiver Noise, Illustrative Problems.

Radar Equation : Modified Radar Range Equation, SNR, probability of detection, probability of False Alarm, Integration of Radar Pulses, Radar Cross Section of Targets (simple targets - sphere, cone-sphere), Creeping Wave, Transmitter Power, PRF and Range Ambiguities, System Losses (qualitative treatment), Illustrative Problems.

UNIT-II:

CW and Frequency Modulated Radar : Doppler Effect, CW Radar – Block Diagram, Isolation between Transmitter and Receiver, Non-zero IF Receiver, Receiver Bandwidth Requirements, Applications of CW radar. Illustrative Problems

FM-CW Radar: Range and Doppler Measurement, Block Diagram and Characteristics, FM-CW altimeter, Multiple Frequency CW Radar.

UNIT-III:

MTI and Pulse Doppler Radar: Introduction, Principle, MTI Radar with - Power Amplifier Transmitter and Power Oscillator Transmitter, Delay Line Cancellers – Filter Characteristics, Blind Speeds, Double Cancellation, N^{th} Cancellation Staggered PRFs. Range Gated Doppler Filters. MTI Radar Parameters, Limitations to MTI Performance, MTI versus Pulse Doppler Radar.

UNIT -IV:

Tracking Radar: Tracking with Radar, Sequential Lobing, Conical Scan, Mono pulse Tracking Radar – Amplitude Comparison Mono pulse (one- and two- coordinates), Phase Comparison Mono pulse, Tracking in Range, Acquisition and Scanning Patterns, Comparison of Trackers.

UNIT -V:

Detection of Radar Signals in Noise : Introduction, Matched Filter Receiver – Response Characteristics and Derivation, Correlation detection and Cross-correlation Receiver, Efficiency of Non-matched Filters, Matched Filter with Non-white Noise, Noise Figure and Noise Temperature.

UNIT -VI:

Radar Receivers –Displays – types. Duplexers – Branch type and Balanced type, Circulators as Duplexers. Introduction to Phased Array Antennas – Basic Concepts, Radiation Pattern, Beam Steering and Beam Width changes, Series versus parallel feeds, Applications, Advantages and Limitations. Radomes.

TEXT BOOKS:

1. Introduction to Radar Systems – Merrill I. Skolnik, TMH Special Indian Edition, 2nd Ed., 2007.

REFERENCE BOOKS:

1. Introduction to Radar Systems, 3rd edition – M.I. Skolnik, TMH Ed., 2005
2. Radar: Principles, Technology, Applications – Byron Edde, Pearson Education, 2004.
3. Radar Principles – Peebles, Jr., P.Z., Wiley, New York, 1998.
4. Principles of Modern Radar: Basic Principles – Mark A. Richards, James A. Scheer, William A. Holm, Yesdee,
5. Radar Engineering – GSN Raju, IK International.

OUTCOMES**After going through this course the student will be able to:**

1. Derive the radar range equation and to solve some analytical problems.
2. Understand the different types of radars and its applications.
3. Understand the concept of tracking and different tracking techniques.
4. Understand the various components of radar receiver and its performanc.